

BMEG 3105: Data Analytics for Personalized Genomics and Precision Medicine

Lecture 21 – Deep learning & Biomedical imaging

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1. Review last lecture

-Challenges in single-cell data analytics

Noise

Doublet

Dropout

Batch effect

-Visualize gene expression data in 2D

High dimension to 2D

-The process of t-SNE

-Protein binding preference

2. Artificial intelligence VS Machine learning VS Deep learning

-Health data

Diagnosing based on the symptom and lab tests

Curing the disease based on the diagnosing results and the patient's situation

Without the data, doctors cannot diagnose precisely

AI + Health data: AI-assisted disease **diagnosing** and **curing**

-AI vs ML vs DL

Artificial Intelligence (AI):

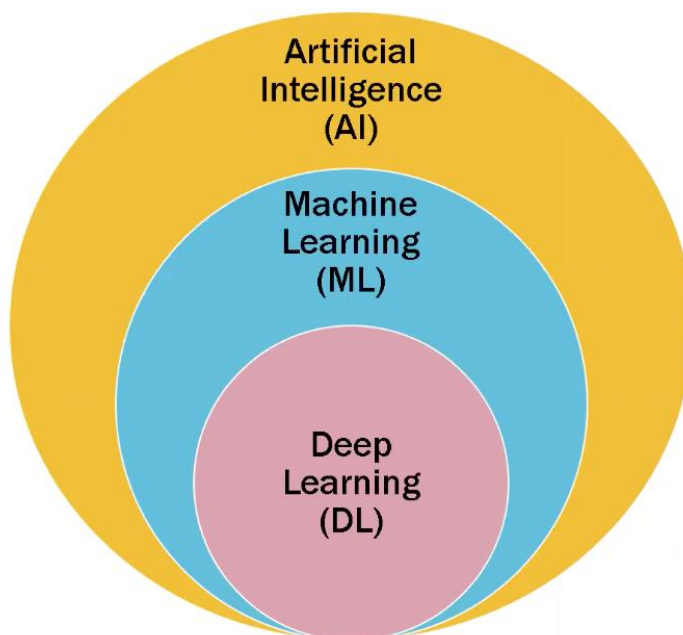
Any techniques which enable computers to **mimic human behavior**

Machine Learning (ML):

A subset of AI, which effectively perform a specific task **without using explicit instructions**, relying on patterns and inference from the data

Deep Learning (DL):

A subset algorithm of ML, which takes advantage of **multi-layer neural networks**



-Machine learning tasks

-Unsupervised learning:

-Dimensionally reduction;

-Clustering.

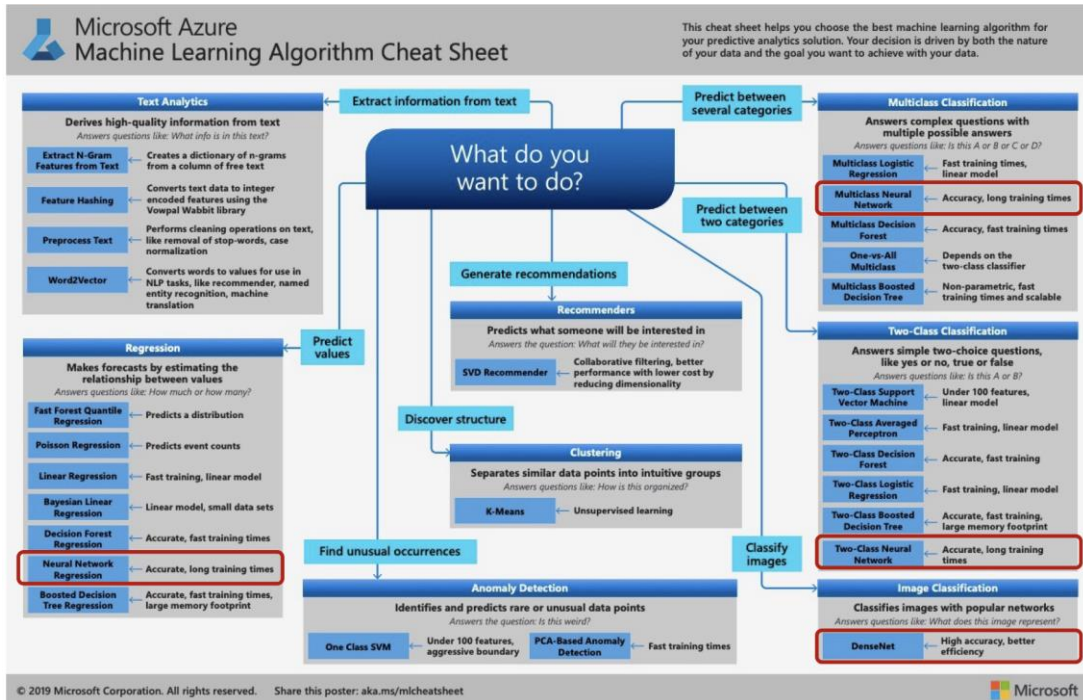
-Supervised learning:

-Classification;

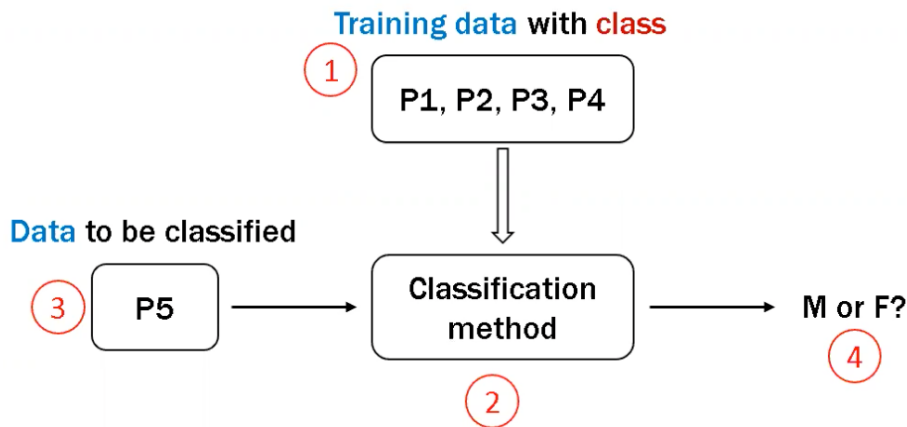
-Regression.

-Reinforcement learning.

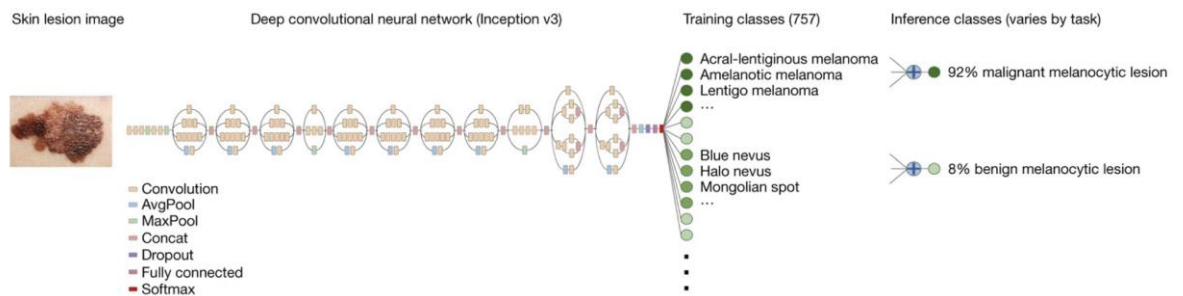
-Machine learning algorithms



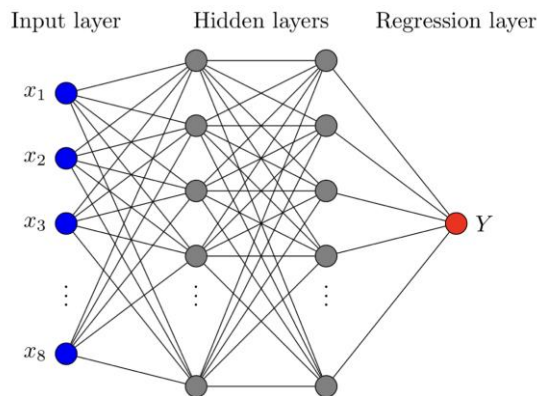
3. Deep learning and biomedical imaging



-Build models for real-life healthcare problems



-Fully-connected networks



❖ To resolve complicated problems

- Increase the number of nodes
- Increase the number of layers
- Add non-linear function

❖ Fully-connected layers

- A general function approximator
- We can approximate any function (relation) if we have enough nodes and layers
- Universal approximation theorem

-The problem of fully-connected networks:

- How to determine the number of nodes and layers
- Storage
- Running time
- Hard to train
- Prior knowledge is ignored
- Overfitting

-Image

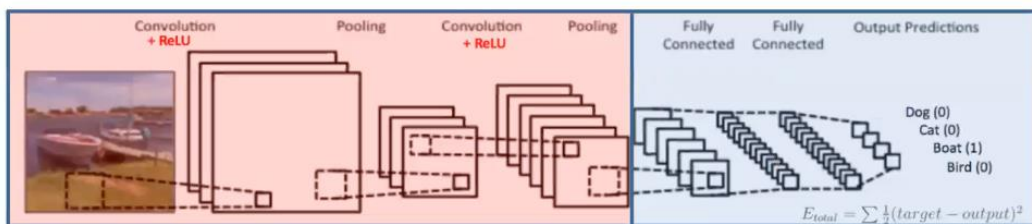
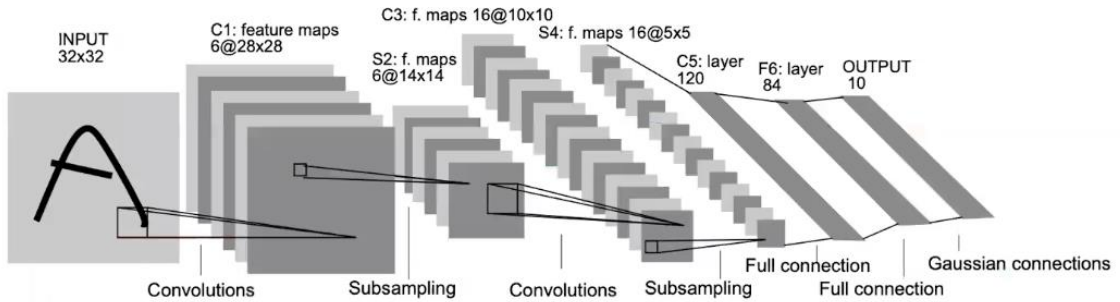
Images are different from data matrix----there is **spatial information** in the image----we should design models based on that.

-Properties of objects in the images

-Translation invariance: Capture the patch information, no matter where it is.

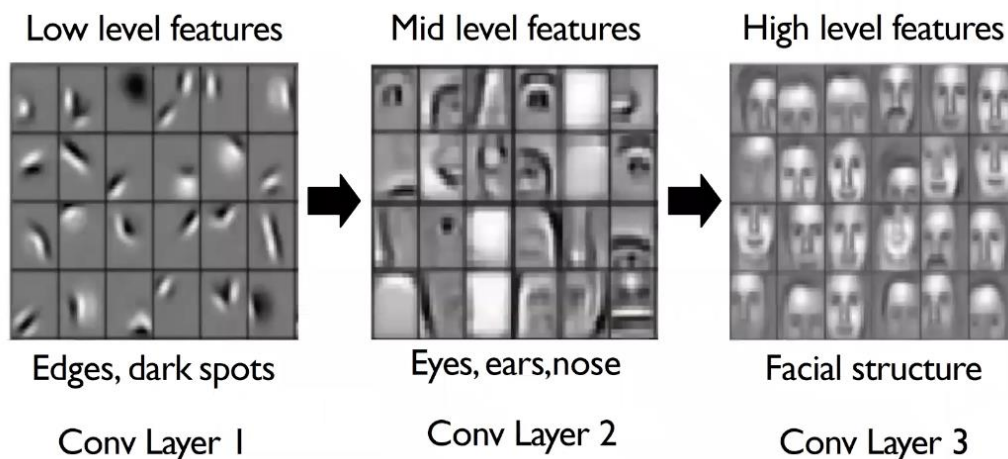
-Locality: Focus on the local regions first; should be aggregated later on.

-Convolutional layers



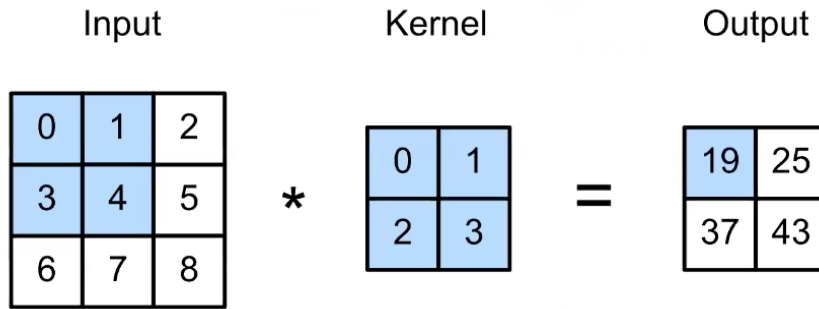
Hierarchical representation learning feature extraction---->

Fully-connected neural networks classification



Things we can get from CNN: spatial pattern

-Convolution operation



$$19 = 0*0 + 1*1 + 2*3 + 3*4$$

$$25 = 0*1 + 1*2 + 2*4 + 3*5$$

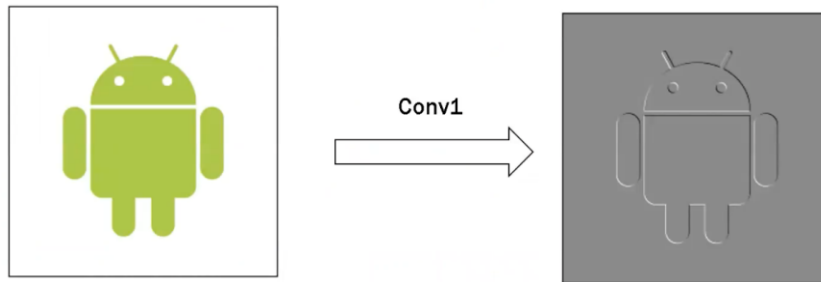
$$37 = 0*3 + 1*4 + 2*6 + 3*7$$

$$43 = 0*4 + 1*5 + 2*7 + 3*8$$

How to do convolution:

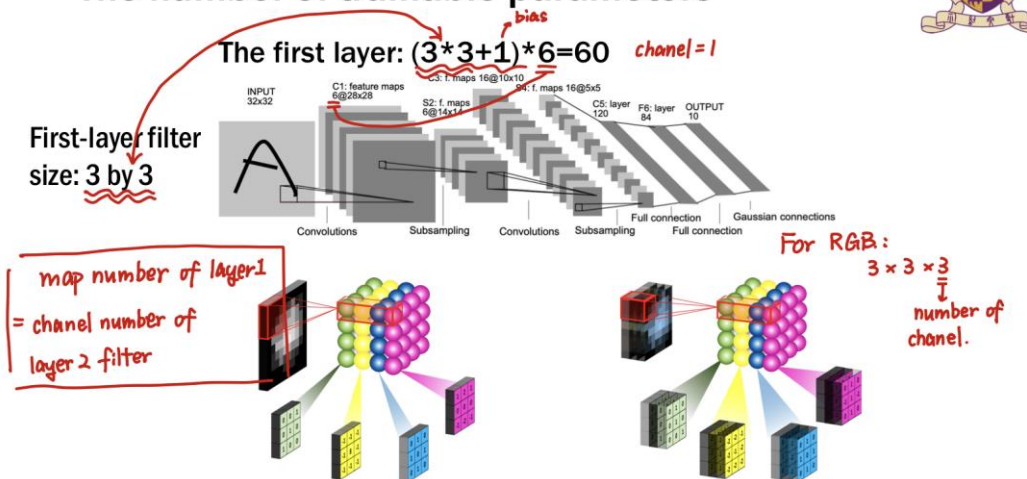
Share parameters—Alleviate the overfitting issue; detect translation invariant features; locality.

Output:



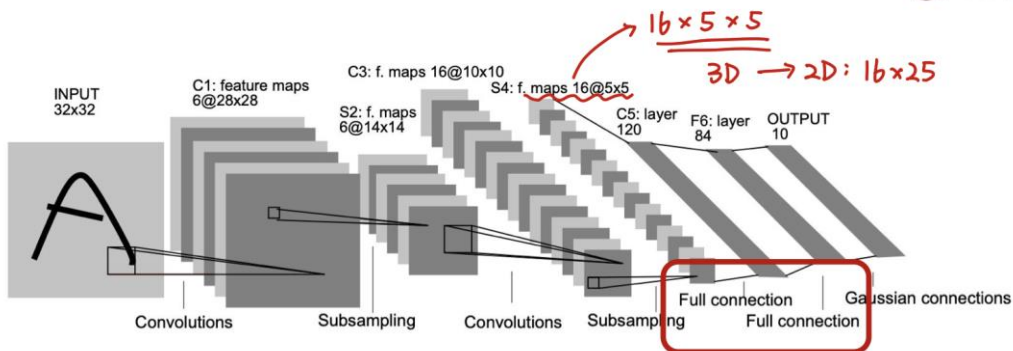
-The number of trainable parameters

The number of trainable parameters



-Flatten layer

Flatten layer



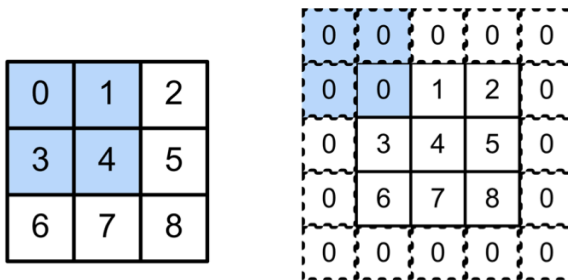
4. More discussion of convolutional layer

-Filter size

Usually 3 by 3 or 5 by 5

-How to deal with boundary

Padding: add zeros

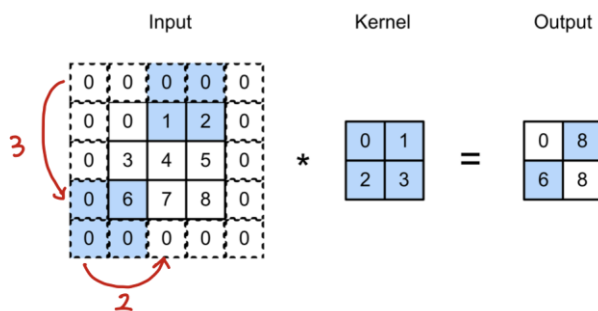


The output dimension is the same as the input if:

-Kernel: 3 by 3, padding: 1 for each edge

-Kernel: 5 by 5, padding: 2 for each edge

-Stride



Column stride: 2
Row stride: 3

-Pooling

Max pooling; average pooling.

(Also combined with padding and stride)